

UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS										CONDUIT BOX						MAXIMUM WEIGHT	
	A	B	C	D	G	J	K	M	O	P	T	AA	AB	AC	AE	AF		XL
507USS	24.9	24.9	43.6	12.50	1.4	5.6	4.8	19.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7	15.7	11.5
507US	24.9	24.9	48.9	12.50	1.4	5.6	4.8	19.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7	15.7	11.5
507US	10.00	22.00	0.94	8.5	8.5	10.13	9.88	3.375	2.880	0.875	8.50	6320C3	6320C3	6320C3	2900	lbs.		

TAG NO's: _____

CUSTOMER: _____ MOTOR MODEL NO.: _____
 P.O. NO.: _____ HP: _____ VOLTAGE: _____ RPM(SYN.): _____ Hz: _____
 FRAME SIZE: _____ PRODUCT TYPE: ODP EQP III, EPACT, & HIGH EFFICIENCY
 COMMENTS: _____

 PER: _____ DATE: _____

TOSHIBA RESERVES THE RIGHT TO MAKE CHANGES OF TECHNICAL IMPROVEMENT AND THE DATA MAY CHANGE WITHOUT NOTICE PRELIMINARY
 DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED CERTIFIED

- STANDARD (NO AUX. BOXES)
- RTD AUX. BOX
- SPACE HEATER AUX. BOX
- BEARING RTD's

- NOTES:
1. DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT
 2. MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS
 3. KEY DIMENSIONS EQUAL S x S x 8.50 FOR US AND S x S x 3.00 FOR USS (MOTOR SUPPLIED WITH KEY)
 4. MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME
 5. OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE

TOSHIBA

TOSHIBA INTERNATIONAL CORPORATION

OPEN DRIP-PROOF
 HORIZONTAL FOOT-MOUNTED
 3 PHASE INDUCTION MOTOR
 F1 ASSEMBLY

XT SERIES

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 www.toshiba.com/ind

TYPICAL MOTOR PERFORMANCE DATA

Model: B5002VLG3OMH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
500	373	2	3570	507USS	575	60	3	421.00
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	96.5	B	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	500	372.9	421.0	96.5	92.4
¾ Load	375.00	279.6	315.6	96.8	91.8
½ Load	250.00	186.4	217.9	96.8	89.5
¼ Load	125.00	93.2	127.5	91.3	80.4
No Load			72.0		5.2
Locked Rotor			2900		23.7

Torque				Rotor wk ² Inertia (lb-ft ²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
735	175	160	340	91.81

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
18	8	-	6313C3	6313C3	2777

*Bearings are the only recommended spare part(s).

Motor Options:
Product Family:ODP
Mounting:Footed,Shaft:USS Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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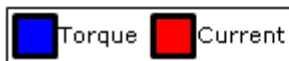
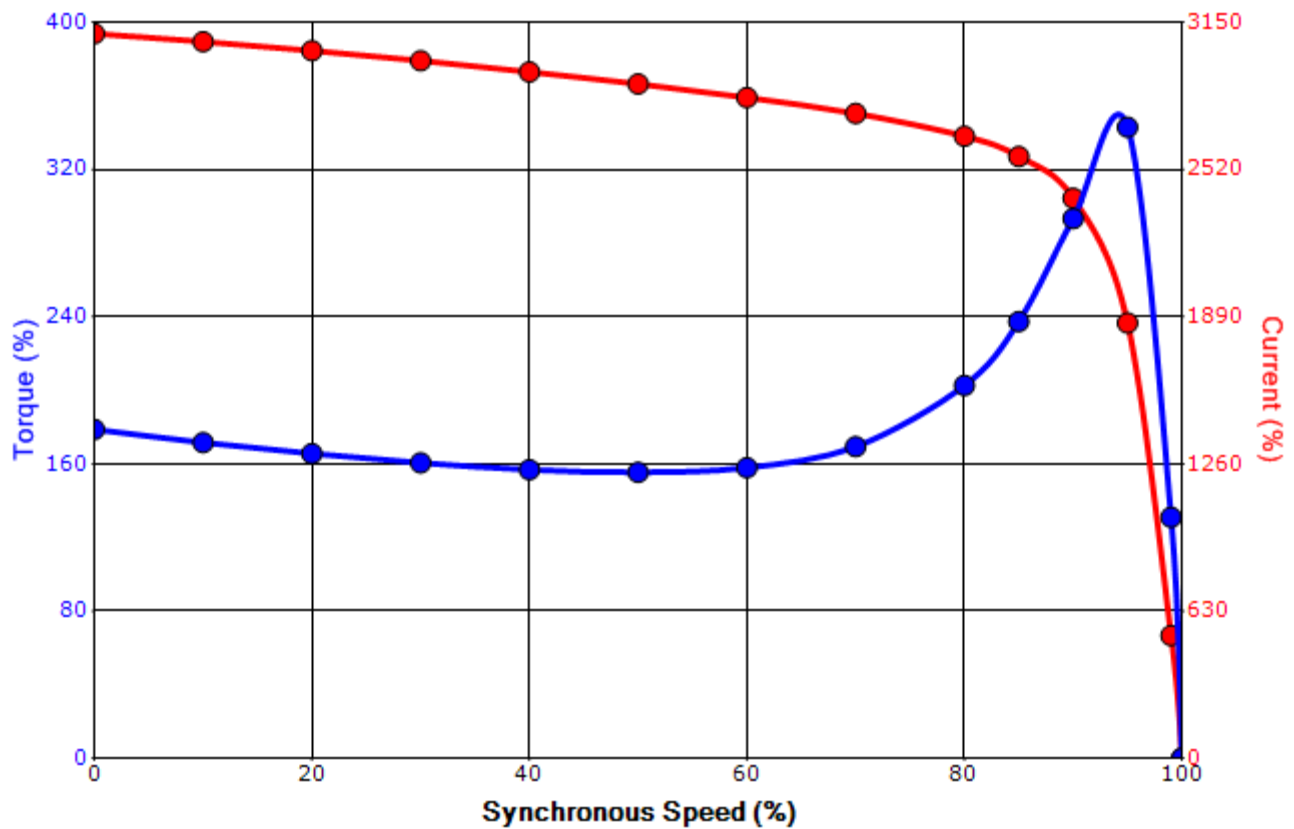
Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	5/21/2012	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: B5002VLG3OMH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
500	373	2	3570	507USS	575	60	3	421.00
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	96.5	B	G	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						Break Down (%)
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)				
2900	91.81	735	175	160			340	

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

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Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
Engr. Date	5/21/2012	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

Motor Connection Diagrams
6 Leads

Across the Line Starting / Run - Delta:



Alternate Starting Connection - Wye:



Switch L1 and L2 to reverse rotation