

UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS										CONDUIT BOX							
	A	B	C	D	G	J	K	M	O	P	T	AA	AB	AC	AE	AF	XL	XN
507USS	24.9	24.9	43.6	12.50	1.4	5.6	4.8	19.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7	15.7	11.5
507US	24.9	24.9	48.9	12.50	1.4	5.6	4.8	19.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7	15.7	11.5
FRAME SIZE	MOUNTING				SHAFT EXTENSION				KEY SEAT				BEARINGS				MAXIMUM WEIGHT	
	E	2F	H	BA	N-W	V	U	R	S	ES	LS	OS						
507USS	10.00	22.00	0.94	8.5	4.75	4.50	2.375	2.021	0.625	3.00	6313C3	6313C3					2900 lbs.	
507US	10.00	22.00	0.94	8.5	10.13	9.88	3.375	2.880	0.875	8.50	6320C3	6320C3					2900 lbs.	

- NOTES:
1. DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT
 2. MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS
 3. KEY DIMENSIONS EQUAL S x S x 8.50 FOR US AND S x S x 3.00 FOR USS (MOTOR SUPPLIED WITH KEY)
 4. MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME
 5. OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE

CUSTOMER: _____ MOTOR MODEL NO.: _____ TAG NO's.: _____

P.O. NO.: _____ HP: _____ VOLTAGE: _____ RPM(SYN.): _____ Hz: _____

FRAME SIZE: _____ PRODUCT TYPE: ODP EQP III, EPACT, & HIGH EFFICIENCY

COMMENTS: _____

PER: _____ DATE: _____

TOSHIBA RESERVES THE RIGHT TO MAKE CHANGES OF TECHNICAL IMPROVEMENT AND THE DATA MAY CHANGE WITHOUT NOTICE PRELIMINARY

DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED CERTIFIED

STANDARD (NO AUX. BOXES)

RTD AUX. BOX

SPACE HEATER AUX. BOX

BEARING RTD's

TOSHIBA

OPEN DRIP-PROOF
HORIZONTAL FOOT-MOUNTED
3 PHASE INDUCTION MOTOR
F1 ASSEMBLY

TOSHIBA INTERNATIONAL CORPORATION

XT SERIES

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TYPICAL MOTOR PERFORMANCE DATA

Model: F6002VLG3OMH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
600	447	2	3570	507USS	575	60	3	510.00
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	96.2	-	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	600	447.4	510.0	96.2	92.4
¾ Load	450.00	335.6	383.7	95.7	91.9
½ Load	300.00	223.7	277.5	95.7	89.7
¼ Load	150.00	111.9	188.0	91.5	65.3
No Load			80.0		5.0
Locked Rotor			3380		23.7

Torque				Rotor wk ²
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	Inertia (lb-ft ²)
883	120	110	235	79.43

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
5.6	2.1	-	6313C3	6313C3	2777

*Bearings are the only recommended spare part(s).

Motor Options:
Product Family:ODP
Mounting:Footed,Shaft:USS Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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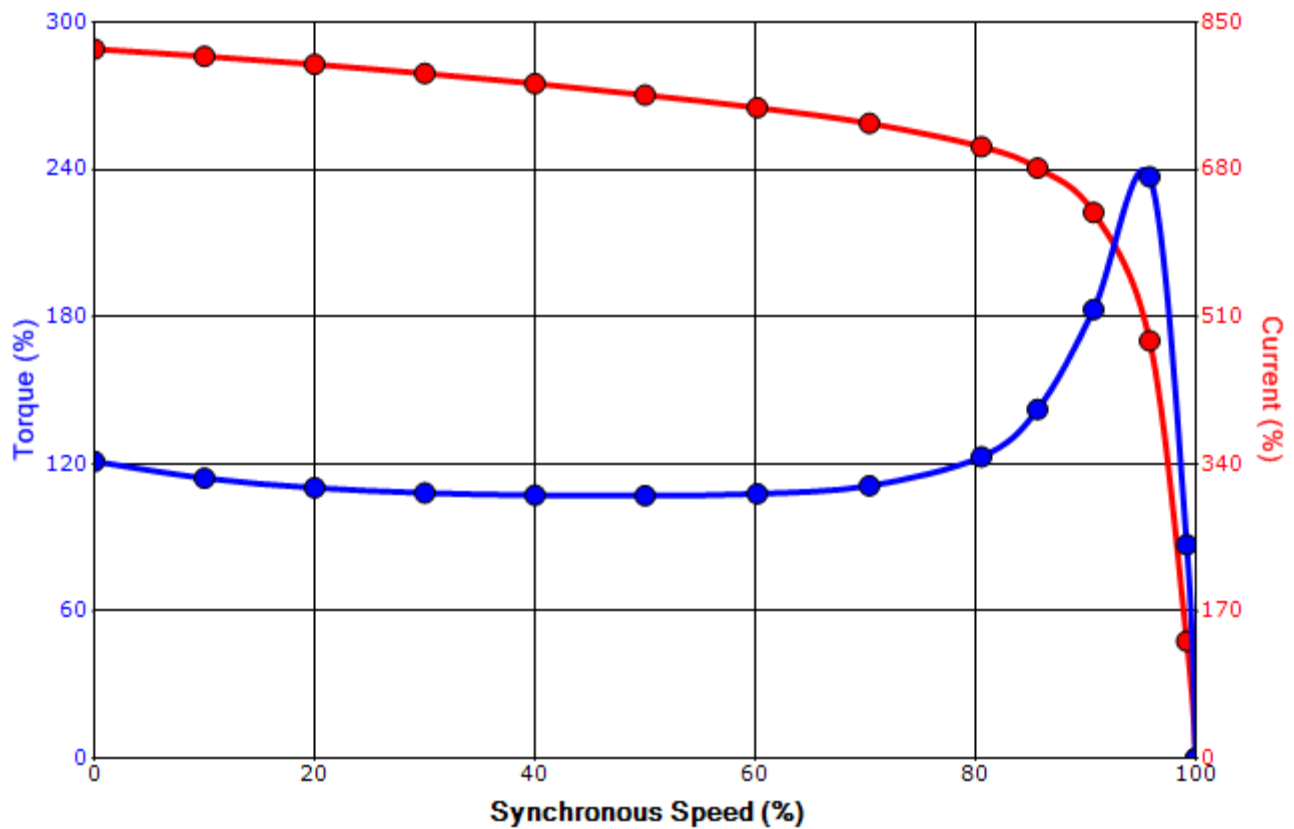
Engineering	jaustin	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	7/24/2014	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: F6002VLG30MH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
600	447	2	3570	507USS	575	60	3	510.00
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	96.2	-	G	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						Break Down (%)
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)				
3380	79.43	883	120	110			235	

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

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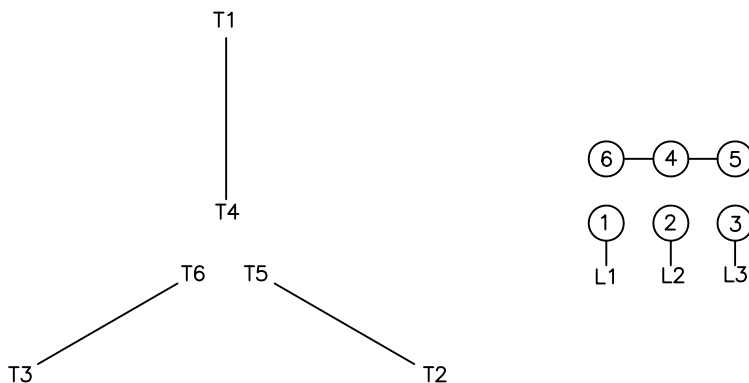
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Motor Connection Diagrams
6 Leads

Across the Line Starting / Run - Delta:



Alternate Starting Connection - Wye:



Switch L1 and L2 to reverse rotation